

Dijkstra's Algorithm

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Weighted Graph, Shortest Path & Negative Cycle

- ▶ $w : E \rightarrow \mathbf{R}$ is known as *weight function*
- ▶ w to an edge is called *weight of the edge*
- ▶ A graph $G = (V, E)$ in which each edge has a weight is called a *weighted graph*.
- ▶ Let $S = v_1, v_2, \dots, v_k$ be a path in a weighted graph G then weight of S is given by

$$w(S) = \sum_{i=1}^{k-1} w(v_i, v_{i+1}).$$

- ▶ A *shortest path* from a vertex v to a vertex v' is defined as any $v - v'$ path S with weight $w(S) = d(v, v')$ where $d(v, v')$ is given by

$$d(v, v') = \begin{cases} \min\{w(\tilde{P}) \mid \tilde{P} \text{ is a } v - v' \text{ path}\} & \text{if } v' \text{ is reachable from } v \\ +\infty & \text{otherwise.} \end{cases}$$

- ▶ A cycle C in a weighted graph with $w(C) < 0$ is called a *negative cycle*.

Dijkstra's Algorithm (Main Idea)

- ▶ The idea is to visit the nodes in order of their closeness to *source vertex* s .

The closest node to s , say x , must be adjacent to s and the next closest node, say y , must be either adjacent to s or x . The third closest node to s must be either adjacent to s or x or y , and so on.

Predecessor $\pi[v]$ & Shortest Path Estimate $d[v]$

We set the π attribute so that the chain of predecessors originating at a vertex v runs backwards along the shortest path from vertex s to v .

- ▶ Given a graph $G(V, E)$, we maintain for each vertex $v \in V$ a predecessor $\pi[v]$ that is either a vertex or NIL

For each vertex $v \in V$, we maintain an attribute $d[v]$, which is an upper bound on the weight of a shortest path from source s to vertex v .

- ▶ We call $d[v]$ a *Shortest Path Estimate*

Initialize . . .

We initialize the Shortest Path Estimate and Predecessor by the following procedure:

INITIALIZE-SINGLE-SOURCE (G, s)

1. **for** each vertex $v \in V$
2. **do** $d[v] \leftarrow \infty$
3. $\pi[v] \leftarrow \text{NIL}$
4. $d[s] = 0$

After initialization, $\pi[v] = \text{NIL}$, $d[v] = 0$ for $v = s$ and $d[v] = \infty$ for all $v \in V - s$

Relaxation

- ▶ The process of relaxing an edge (u, v) consist of testing whether we can improve the shortest path to v found so far by going through u and, if so, update $d[v]$ and $\pi[v]$.

A relaxation step may decrease the shortest path estimate $d[v]$ and updates's v 's predecessor field $\pi[v]$.

RELAX (u, v, w)

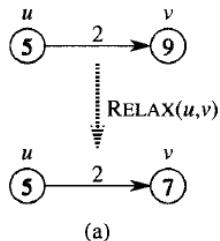
1. **if** $d[v] > d[u] + w(u, v)$
2. **then** $d[v] \leftarrow d[u] + w(u, v)$
3. $\pi[v] \leftarrow u$

Relaxation

RELAX (u, v, w)

1. **if** $d[v] > d[u] + w(u, v)$ (if new shortest path found)
2. **then** $d[v] \leftarrow d[u] + w(u, v)$ (set new value of shortest path)
3. $\pi[v] \leftarrow u$ (add u to predecessor of v)

Relaxation of an edge (u, v).



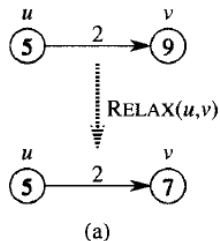
- (a) Because $d[v] > d[u] + w(u, v)$ prior to relaxation, the value of $d[v]$ decreases.

Relaxation

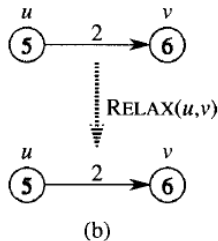
RELAX (u, v, w)

1. **if** $d[v] > d[u] + w(u, v)$ (if new shortest path found)
2. **then** $d[v] \leftarrow d[u] + w(u, v)$ (set new value of shortest path)
3. $\pi[v] \leftarrow u$ (add u to predecessor of v)

Relaxation of an edge (u, v).



(a) Because $d[v] > d[u] + w(u, v)$ prior to relaxation, the value of $d[v]$ decreases.



(b) Here, $d[v] \leq d[u] + w(u, v)$ before the relaxation step, so $d[v]$ is unchanged by relaxation.

Dijkstra's Algorithm

Dijkstra's algorithm maintains a set S of those vertices for which the shortest path weights from the source s have already been determined. The algorithm repeatedly selects the vertices $u \in V \setminus S$ with shortest path estimates, and inserts u into S , and relaxes all the edges leaving u . In the following implementation, we maintain a priority queue Q that contains all the vertices in $V \setminus S$ keyed by their d values.

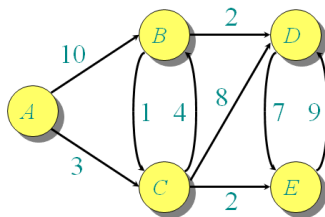
Dijkstra's Algorithm

DIJKSTRA (G, w, s)

- 1 INITIALIZE-SINGLE-SOURCE (G, s) (distance to source vertex is zero)
(set all other distances to infinity)
- 2 $S \leftarrow \emptyset$ (S , the set of visited vertices is initially empty)
- 3 $Q \leftarrow V[G]$ (Q , the queue initially contains all vertices)
- 4 **while** $Q \neq \emptyset$ (while the queue is not empty)
- 5 **do** $u \leftarrow EXTRACT - MIN(Q)$ (select the element of Q with the min. distance)
- 6 $S \leftarrow S \cup \{u\}$ (add u to list of visited vertices)
- 7 **for** each vertex $v \in Adj[u]$
- 8 **do** RELAX(u, v, w) (if new shortest path found)
(set new value of shortest path)

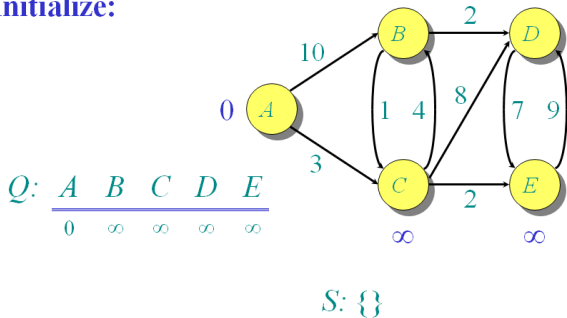
Dijkstra's Algorithm Implementation

**Graph with
nonnegative
edge weights:**

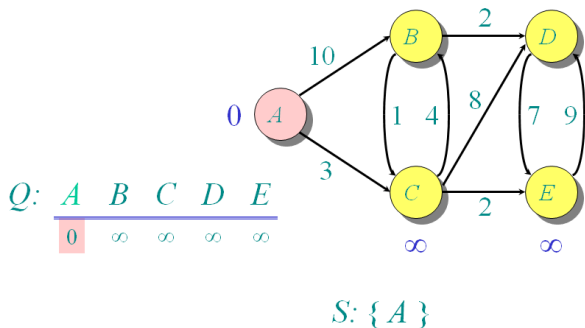


Dijkstra's Algorithm Implementation

Initialize:

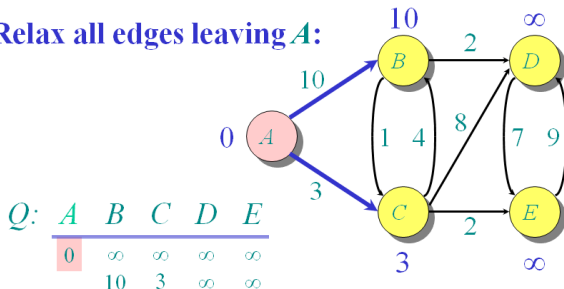


Dijkstra's Algorithm Implementation



Dijkstra's Algorithm Implementation

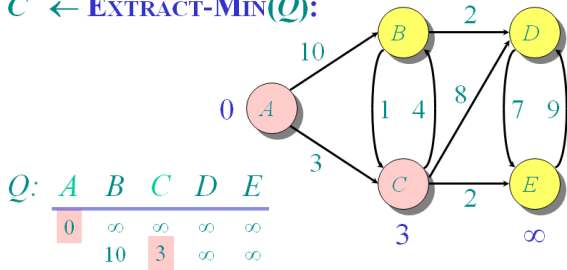
Relax all edges leaving A :



$S: \{A\}$

Dijkstra's Algorithm Implementation

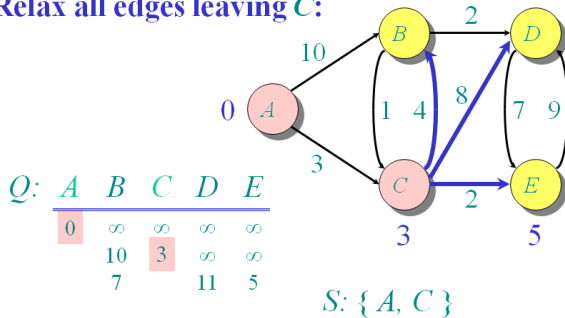
"C" ← EXTRACT-MIN(Q):



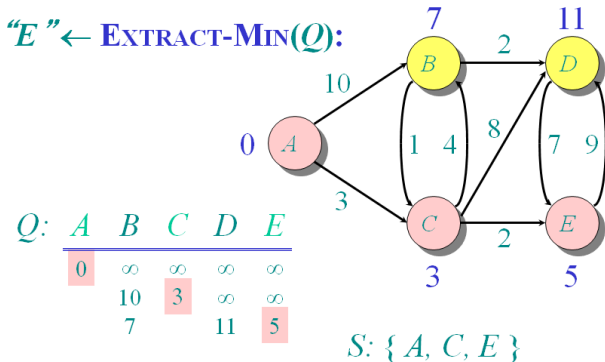
S: {A, C}

Dijkstra's Algorithm Implementation

Relax all edges leaving C :

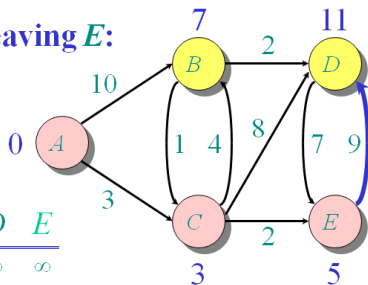


Dijkstra's Algorithm Implementation



Dijkstra's Algorithm Implementation

Relax all edges leaving E :

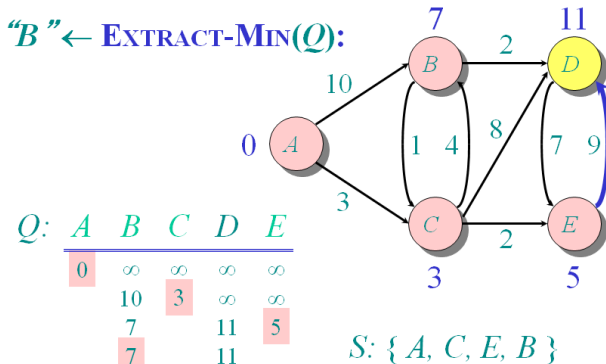


Q :

A	B	C	D	E
0	∞	∞	∞	∞
	10	3	∞	∞
	7		11	5
	7		11	

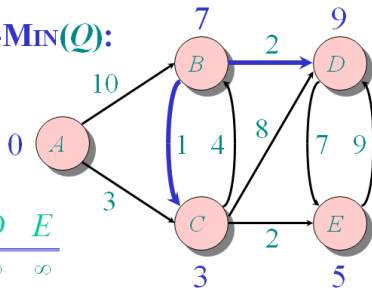
$S: \{A, C, E\}$

Dijkstra's Algorithm Implementation



Dijkstra's Algorithm Implementation

"D" ← EXTRACT-MIN(Q):



Q:	A	B	C	D	E
	0	∞	∞	∞	∞
		10	3	∞	∞
		7		11	5
		7		11	
				9	

S: {A, C, E, B, D}

